

4/6/25 From CFM to Diffusion

- Comment about CFM: not limited to Gaussian paths! Any path from $\delta(x-x_0)$ to $\mathcal{N}(0,1)$
 $p_1(x|x_1)$ $p_0(x|x_0)$
will work to generate $x_1 \sim p_{\text{data}}$.

- $$\begin{cases} p_+(x) = \int dz p_+(x|z) g(z) \\ u_+(x) = \int dz p_+(x|z) u_+(x|z) g(z) \end{cases}$$
$$\underline{\underline{p_+(x)}}$$

Generalizes to any $g(z)$ w/ correct bdy cond.

Tong et al

2302.0482

Ex: $g(z) = \pi(z_0, z_1)$

$$\pi(z_0) = g_0(z_0) \quad \text{base}$$

$$\pi(z_1) = g_1(z_1) \quad \text{target}$$

$$p_0(x|z_0, z_1) = \delta(x-z_0) \quad p_1(x|z_0, z_1) = \delta(x-z_1)$$

Can FM from any two c.r.b. distributions
(just need samples)

$$\pi(z_0, z_1) = q_0(z_0) q_1(z_1) \text{ reduces to prev.}$$

$$\pi_1(z_0, z_1) = \sqrt{T} s_0 / n \rightarrow \text{can try to learn}$$

Diffusion Generative Models ~ 2020-2021

Consider Markov noise process

$$dx_t = f(t) x_t dt + g(t) dw$$

Wiener process

Brownian motion

drift "stochastic diff eq" diffusion

mean: in time dt Gaussian

x_t shifted by random variable

$$w / \text{mean } f(t) x_t dt$$

$$\& \text{variance } \sigma^2 = g(t)^2 dt$$

$$dw \sim \sqrt{dt} \epsilon \sim N(0,1)$$

first time

GANs surpassed

in image quality,
mode collapse, ...

Sol'n to this SDE is

$$x_t \sim N(\bar{x}_t, \sigma_t) \sim / \begin{cases} \frac{\dot{\bar{x}}_t}{\sigma_t} = f(t) \\ \sqrt{2\sigma_t^2 \left(\frac{\dot{\sigma}_t}{\sigma_t} - \frac{\dot{\bar{x}}_t^2}{\sigma_t^2} \right)} = g(t) \end{cases}$$

Deriv (SKIP)

$$x_t \sim N(\bar{x}_t, \sigma_t)$$

$$dx_t \sim N(f(t)x_t dt, g(t)\sqrt{dt})$$

$$p(x_{t+dt}) = \int dx_t p(x_t) d(dx_t) p(dx_t) \delta(x_{t+dt} - x_t - dx_t)$$

$$\Rightarrow \rightarrow N(\bar{x}_{t+dt}, \sigma_{t+dt})$$

$\rightarrow$ derive diff eqs relaty $\dot{\bar{x}}_t$ & $\dot{\sigma}_t$
to f & g .

Same gaussian prob path from

$$N(0,1) \text{ to } \delta(x - x_1)$$

as in FM! — but use SDE
instead of ODE

Yang Song, Ermon & others realized:

Can also reverse noise $\rightarrow$ data

"reverse diffusion" using "Langevin eqn" (from theory of SDEs & Brownian motion)

$$dx_t = (f(t)x_t - g(t)^2 \nabla_{x_t} \log p_t(x_t))dt + g(t)dw$$

Solve SDE in reverse,

start w/ noise dist'n, end up w/ data dist'n!

$\nabla_{x_t} \log p_t(x_t)$ "score fn"

Note: learning $\nabla_x \log p$ should be easier than learning $p \rightarrow$ don't need normalization

$p = e^{-\epsilon/\tau}$ "energy based models"

Trick to learn $\nabla_x \log p_t$:

"conditional score matching"
(just like CFM)

• learn instead $\nabla_{x_t} \log p_t(x_t | x_1)$

$$\begin{aligned} & \mathcal{N}(x_t | \delta_t x_1, \sigma_t^2) \\ & \sim \frac{x_t - \delta_t x_1}{\sigma_t^2} \end{aligned}$$

• Claim: $L_{SM}(\theta) = \mathbb{E}_{\substack{t \sim \mathcal{U}(0,1) \\ x_t \sim p_t(x_t)}} \|S_\theta(x_t, t) - \nabla_{x_t} \log p_t(x_t)\|^2$

$$= L_{SM}(\theta) + \text{const}$$

$$\begin{aligned} & \mathbb{E}_{\substack{t \sim \mathcal{U}(0,1) \\ x_t \sim p_t(x_t | x_1) \\ x_1 \sim p_{\text{data}}}} \|S_\theta(x_t, t) - \nabla_{x_t} \log p_t(x_t | x_1)\|^2 \end{aligned}$$

$$Pf: \int dt \int dx_+ \rho_+(x_+ | x_1) dx_1 \rho_{data}(x_1) \\ \left(\underbrace{\checkmark}_{\rho_+(x_+ | x_1)} \left(\checkmark_{\rho_+(x_+ | x_1)} \sigma^2 - 2\sigma \nabla_{x_+} \rho_+(x_+ | x_1) \right) + \text{const} \right)$$

integrate over x_1

$$\rho_+(x_+) \sigma^2 - 2\sigma \nabla_{x_+} \rho_+(x_+) \quad \checkmark$$

as in CFM, get extremely simple objective for learning score!

σ can be any NN, not restricted

Very reminiscent of CFM!

No consideration — vector field
& score closely related

In fact can show:

$$u_t(x_t) = f(t)x_t - \frac{1}{2} s(t)^2 s_t(x_t)$$

valid only for Gaussian path

— score-based diffusion is special case of CFM!

$$p_f \text{ (can skip)} : \dot{\sigma}_t x_t + \frac{(\dot{\sigma}_t - \dot{\sigma}_t)}{\sigma_t} x_t$$

$$u_t(x_t) = \int dx_1 u_t(x_t | x_1) p_t(x_t | x_1) p_{data}(x_1)$$

$$p_t(x_t) \downarrow$$

$$e^{-\frac{(x_t - \sigma_t x_1)^2}{2\sigma_t^2}}$$

$$= () x_t + \int dx_1 () x_1 e^{-\frac{(x_t - \sigma_t x_1)^2}{2\sigma_t^2}} p_{data}(x_1)$$

$$= () x_t + \mathbb{E}_{x_1 \sim p_t(x_t)} u_t(x_1)$$

So score-matchy & flow-matchy

$$\|u_\theta - u_\psi(x_t|x_1)\|^2 \text{ vs}$$

$$\|s_\theta - \nabla_{x_t} \log P_\psi(x_t|x_1)\|^2$$

just two equiv losses!

- Diffusion samplg vs CFM samplg
(SDG) (ODE)
just another choice!

All part of a common framework
~ CNF.